

MOTDim d

Hadrien De March

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Work to be done

Martingale Optimal Transport in Higher Dimension

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Under the direction of Nizar Touzi

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CMAP

Renoulez, admettez vos conflits
avec le Centre de Médiation et d'Arbitrage de Paris



Outline

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The Monge optimal transport problem

Originally a soil moving problem for building.

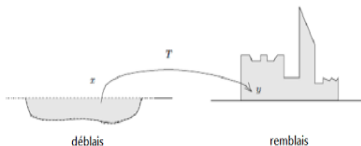


Figure: The Monge problem illustrated.



Figure: The cost of moving building brick.

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Probabilistic optimal transport

Kantorovitch has been the one making this problem probabilistic, so that it becomes a linear problem.

- $(\Omega, \mathcal{E}) = (\mathbb{R}^d \times \mathbb{R}^d, \mathcal{B}(\mathbb{R}^d \times \mathbb{R}^d))$
- X and Y the two canonical random variables $\Omega \rightarrow \mathbb{R}^d$,
 $X : (x, y) \mapsto x$ and $Y : (x, y) \mapsto y$.
- $\mathcal{P}(\mu, \nu) := \{\mathbb{P} \in \mathcal{P}(\mathbb{R}^d \times \mathbb{R}^d) / \mathbb{P} \circ X^{-1} = \mu, \mathbb{P} \circ Y^{-1} = \nu\}$
the set of all coupling probability laws between μ and ν .

Definition

The optimal transport problem is:

$$\mathbf{P} = \inf_{\mathbb{P} \in \mathcal{P}(\mu, \nu)} \mathbb{E}^{\mathbb{P}}(c(X, Y))$$

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The dual problem

We define the dual set:

$$\mathcal{D}_{\mu,\nu}(c) = \left\{ (\phi, \psi) \in L^1(\mu) \times L^1(\nu), \right. \\ \left. \forall x, y \in \mathbb{R}^d, c(x, y) \geq \phi(x) + \psi(y) \right\}$$

Definition

The dual problem is

$$\mathbf{D} := \sup_{(\phi, \psi) \in \mathcal{D}_{\mu, \nu}(c)} \mu(\phi) + \nu(\psi)$$

Remark

If $(\phi, \psi) \in \mathcal{D}_{\mu, \nu}(c)$ and $\mathbb{P} \in \mathcal{P}(\mu, \nu)$ then

$$\mathbb{E}^{\mathbb{P}}[c(X, Y)] \geq \mathbf{P} \geq \mathbf{D} \geq \mathbb{P}[\phi(X) + \psi(Y)] = \mu(\phi) + \nu(\psi)$$

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Kantorovitch Duality

The parallel study of these two problems is justified by the following theorem:

Theorem

If the cost c is lower semicontinuous and dominated by $a \oplus b \in L(\mu) \oplus L(\nu)$, then

- *There is duality: $\mathbf{P} = \mathbf{D}$.*
- *There are optimizers $(\phi^*, \psi^*) \in \mathcal{D}_{\mu, \nu}(c)$ for \mathbf{D} and $\mathbb{P}^* \in \mathcal{P}(\mu, \nu)$ for \mathbf{P} .*
- *There is a Borel support $\Gamma \subset \mathbb{R}^{2d}$ such that $\mathbb{P} \in \mathcal{P}(\mu, \nu)$ is concentrated on Γ if and only if it is optimal.*

Proof

$$\mathbb{E}^{\mathbb{P}^*} [c(X, Y) - \phi^*(X) - \psi^*(Y)] = \mathbf{P} - \mathbf{D} = 0$$

and $c(X, Y) - \phi^*(X) - \psi^*(Y) \geq 0$.

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Useful cost functions

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- $(x, y) \mapsto d(x, y)$ where $d(\cdot, \cdot)$ is a distance.
- $(x, y) \mapsto |x - y|^2$
- $(x, y) \mapsto |x - y|$

Definition

We define the p -Wasserstein distance for $p \geq 1$: for $\mu, \nu \in \mathcal{P}(\mathbb{R}^d)$,

$$W^p(\mu, \nu) := \left(\inf_{\mathbb{P} \in \mathcal{P}(\mu, \nu)} \mathbb{E}^{\mathbb{P}}[|X - Y|^p] \right)^{\frac{1}{p}}$$

$(\mathcal{P}(\mathbb{R}^d), W^p)$ is a Polish space.

The Monge-Ampere Equation

How to compute the optimal transport in practice ? Equation on the dual optimizer:

Theorem

- $\mu(dx) = f(x)dx$ and $\nu(dy) = g(y)dy$
- $y \mapsto \partial_x c(x, y)$ is injective

Then $\mathbb{P}^*[Y = T(X)] = 1$ with $T(x) = \partial_x c(x, \cdot)^{-1}(\phi(x))$

$$\text{Det}(-D^2\phi(x) + \partial_{xx}c(x, T(x))) = |\text{Det}(\partial_{x,y}c(x, T(x)))| \frac{f(x)}{g(T(x))}$$

If $c(x, y) = -x \cdot y$, we get the Monge-Ampere equation:

$$\text{Det}(-D^2\phi(x)) = \frac{f(x)}{g(T(x))}$$

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Armadillo to ball optimal transport

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Example: Optimal transport from Armadillo to ball.

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Change in the Primal and the Dual Problems

Definition

The martingale optimal transport problem and its dual are:

$$\mathbf{P} = \sup_{\mathbb{P} \in \mathcal{M}(\mu, \nu)} \mathbb{E}^{\mathbb{P}}(c(X, Y))$$

and

$$\mathbf{D} := \inf_{(\phi, \psi, h) \in \mathcal{D}_{\mu, \nu}(c)} \mu(\phi) + \nu(\psi)$$

With $\mathcal{M}(\mu, \nu) := \{\mathbb{P} \in \mathcal{P}(\mu, \nu) / \mathbb{E}^{\mathbb{P}}[Y|X] = X \text{ a.s.}\}$ and

$$\mathcal{D}_{\mu, \nu}(c) = \left\{ (\phi, \psi, h) \in L^1(\mu) \times L^1(\nu) \times L(\mathbb{R}^d, \mathbb{R}^d), \right. \\ \left. \forall x, y \in \mathbb{R}^d, c(x, y) \leq \phi(x) + \psi(y) + h(x) \cdot (y - x) \right\}$$

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Application to finance: robust superhedging problem

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Work to be done

- S_t is the price vector of d tradable underlyings.
- We are at time 0 and we consider a payoff $c(S_1, S_2)$.
- We can buy vanilla payoffs $\phi(S_1)$ and $\psi(S_2)$.
- Vanilla prices given by the implied measures μ and ν .
- One delta hedge at time 1. Costs $h(S_1) \cdot S_1$ at time 1 and pays $h(S_1) \cdot S_2$ at time 2.
- We want to cover perfectly the payoff with the superhedging.

$$c(S_1, S_2) \leq \phi(S_1) + \psi(S_2) + h(S_1) \cdot (S_2 - S_1)$$

- Problem: cheapest price of the superhedging

$$\text{price}(\phi(S_1) + \psi(S_2) + h(S_1) \cdot (S_2 - S_1)) = \mu(\phi) + \nu(\psi)$$

Complete Duality in dimension 1

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Work to be done

(Beiglbock-Nutz-Touzi 15) showed that in dimension 1

- Need to consider the $\mathcal{M}(\mu, \nu)$ -quasi sure problem.
- Need to use a "convex moderator" to extend $\mu(\phi) + \nu(\psi)$
- There is duality $\mathbf{P} = \mathbf{D}$ for non negative measurable costs.
- The dual problem has an optimizer (ϕ, ψ, h) .
- \mathbb{R} is decomposed in "irreducible components" convex and stable by $\mathcal{M}(\mu, \nu)$ on which pointwise duality holds.
- There is a monotone set Γ that supports any optimal probability for the primal problem.

Binary optimal models for specific cost functions

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We define for $x \in \mathbb{R}^d$,

$$T(x) := \Gamma_x = \{y \in \mathbb{R}^d / (x, y) \in \Gamma\}$$

(Beiglbock-Juillet 12) or (Henri-Labordere-Touzi 15)

Theorem

We suppose that $d = 1$, $\mu \ll \text{Leb}$ and that $c(x, y) = |x - y|$ or $\partial_{xyy}c > 0$. Then for μ -a.e. $x \in \mathbb{R}$, $\text{Card}(T(x)) \leq 2$

This result allows to get two general optimal mappings $T_d : \mathbb{R} \rightarrow \mathbb{R}$ and $T_u : \mathbb{R} \rightarrow \mathbb{R}$ such that

$$\Gamma = \{(x, T_d(X)), (x, T_u(X)) / x \in \mathbb{R}\}$$

This allows numerical solving.

In higher dimension

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(Ghoussoub-Kim-Lim 2015) studied higher dimension.

- \mathbb{R}^d can be split in convex irreducible components for \mathbb{P}^* the optimal probability and the problem could be split on these components if they had a measurability.
- There are dual optimizers on each components, even if they may not be measurable globally.
- For $c(x, y) = |x - y|$, $\mu \ll \text{Leb}$ and ν atomic, for μ -a.e. $x \in \mathbb{R}^d$, $\text{Card}(T(x)) = d + 1$.
- They conjecture that more generally, in the case of maximization we can find a.e. $\text{Card}(T(x)) = d + 1$.

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The generalized integral

Dual problem: minimizing $\mu(\phi) + \nu(\psi)$. But in general we can have $\nu(\psi) = -\mu(\phi) = \infty$. We need to extend the definition of $\mu(\phi) + \nu(\psi)$ using h^{\otimes} as a compensator:

Definition

We say that $(\phi, \psi) \in L(\mathbb{R}^d)^2$ is linearly moderated if

$$\sup_{\mathbb{P} \in \mathcal{M}(\mu, \nu)} \mathbb{P}|\phi \oplus \psi + h^{\otimes}| < \infty$$

for some $h \in L(\mathbb{R}^d, \mathbb{R}^d)$. Then we define

$$\mu(\phi) \oplus \nu(\psi) := \sup_{\mathbb{P} \in \mathcal{M}(\mu, \nu)} \mathbb{P}[\phi \oplus \psi + h^{\otimes}]$$

We write the set of these couples of functions $L(\mu, \nu)$.

(Notation: $\phi \oplus \psi + h^{\otimes} := \phi(X) + \psi(Y) + h(X) \cdot (Y - X)$)

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Transformation of the dual problem

We need to treat the problem quasi-surely instead of pointwise then.

$$\mathcal{D}_{\mu,\nu}^{qs}(c) := \left\{ (\phi, \psi, h) \in L(\mu, \nu) \times L(\mathbb{R}^d, \mathbb{R}^d) / \right. \\ \left. c \leq \phi \oplus \psi + h^{\otimes}, \quad \mathcal{M}(\mu, \nu)\text{-q.s.} \right\}$$

And redefine **D**:

Definition

$$\mathbf{D}(c) := \inf_{(\phi, \psi, h) \in \mathcal{D}_{\mu,\nu}^{qs}(c)} \mu(\phi) \oplus \nu(\psi)$$

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Irreducible components

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- We get a decomposition of \mathbb{R}^d in irreducible components that depends only on μ and ν .
- We prove that the mapping $x \mapsto C(x)$ is Borel measurable.
- For $A \subset \mathbb{R}^{2d}$,

$$\begin{aligned} & (A_\mu \times \mathbb{R}^d) \cap (\mathbb{R}^d \times A_\nu) \cap \{Y \in \overline{C(X)}\} \subset A \\ \implies & \quad \quad \quad A \text{ is } \mathcal{M}(\mu, \nu) - q.s. \\ \implies & (A_\mu \times \mathbb{R}^d) \cap (\mathbb{R}^d \times A_\nu) \cap \{Y \in C(X)\} \subset A \end{aligned}$$

Where A_μ (resp. A_ν) is some μ -a.s. (resp. ν -a.s.) set

- What happens on the border is not clear yet: we have to do assumptions.

Duality theorems

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With the assumption we have duality theorems:

- $P = D$ for any nonnegative measurable cost.
- The problem disintegrate in subproblems on the irreducible components where the duality is pointwise.

- There Exists a Borel set Γ such that for any optimal probability \mathbb{P}^* ,

$$\mathbb{P}^*[\Gamma] = 1$$

- To have a reciprocal property, we would need that for $(\phi, \psi) \in L(\mu, \nu)$, $\mathbb{P}[\phi \oplus \psi + h^{\otimes}]$ does not depend on $\mathbb{P} \in \mathcal{M}(\mu, \nu)$. (For example when ϕ and ψ are integrable).

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Open questions

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- Understanding what happens on the boundary of the components.
- Find whether $\mathbb{P}[\phi \oplus \psi + h^{\otimes}]$ depends on $\mathbb{P} \in \mathcal{M}(\mu, \nu)$ or not.
- How to solve numerically the "martingale" version of the Monge-Ampere equation ?
- Study the behaviour of the problems if we add another constraint. (Financially speaking, if we add another product in the market).

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Questions ?



Figure: An example of Optimal Transport in practice.